## The flow of a vector field.

Suppose  $\mathbf{F} = P\mathbf{i} + Q\mathbf{j}$  is a vector field in the plane<sup>1</sup> Associated to  $\mathbf{F}$  is its flow which, for each time t is a transformation

$$\mathbf{f}_t(x,y) = (u_t(x,y), v_t(x,y))$$

and which is characterized by the requirements that

(1) 
$$\mathbf{f}_0(x,y) = (x,y)$$

and

(2) 
$$\frac{d}{dt}\mathbf{f}_t(x,y) = \mathbf{F}(\mathbf{f}_t(x,y))$$

That is, for each  $(x, y), t \mapsto \mathbf{f}_t(x, y)$  is a path whose velocity at time t is the vector that  $\mathbf{F}$  assigns to  $\mathbf{f}_t(x, y)$ .

**Example.** Let  $\mathbf{F} = -y\mathbf{i} + x\mathbf{j}$ . Draw a picture of  $\mathbf{F}$ . Note that

$$\mathbf{f}_t(x,y) = (x\cos t - y\sin t, x\sin t + y\cos t).$$

That is,  $\mathbf{f}_t$  is counterclockwise rotation of  $\mathbf{R}^2$  through an angle of t radians.

As a direct consequence of (1) and (2) above find that

$$u_t(x,y) = x + tP(x,y) + t^2r_t(x,y)$$
 and  $v_t(x,y) = y + tQ(x,y) + t^2s_t(x,y)$ .

It follows that

$$\begin{aligned} J_{\mathbf{f}_{t}}(x,y) &= \mathbf{det} \begin{bmatrix} \frac{\partial u_{t}}{\partial x} & \frac{\partial u_{t}}{\partial y} \\ \frac{\partial v_{t}}{\partial x} & \frac{\partial v_{t}}{\partial y} \end{bmatrix} (x,y) \\ &= \begin{bmatrix} 1 + tP_{x}(x,y) + t^{2} \frac{\partial r_{t}}{\partial x}(x,y) & tP_{y}(x,y) + t^{2} \frac{\partial r_{t}}{\partial y}(x,y) \\ tQ_{x}(x,y) + t^{2} \frac{\partial s_{t}}{\partial x}(x,y) & 1 + tQ_{y}(x,y) + t^{2} \frac{\partial s_{t}}{\partial y}(x,y) \end{bmatrix} \\ &= 1 + t(P_{x} + Q_{y})(x,y) + t^{2} z_{t}(x,y). \end{aligned}$$

This implies that

$$\frac{d}{dt}J_{\mathbf{f}_t}(x,y)\Big|_{t=0} = \operatorname{\mathbf{div}} \mathbf{F}(x,y)$$

where we have set

$$\operatorname{div} \mathbf{F} = P_x + Q_y.$$

This yields the following basic formula:

**Theorem.** Suppose R is a bounded region in the domain of  $\mathbf{F}$ . Then

$$\left. \frac{d}{dt} \operatorname{area} \mathbf{f}_t(R) \right|_{t=0} = \iint_R \operatorname{div} \mathbf{F} \, dA$$

Analogous formulae hold in any dimension.

<sup>&</sup>lt;sup>1</sup> Everything we are about to do here directly generalized to any number of dimensions.